

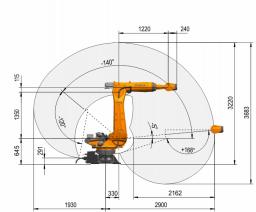


Dimensions: mm

# KR 180 R2900-2



# Workspace graphic



## **Technical data**

Maximum reach	2900 mm
	2900 1111
Rated payload	180 kg
Maximum payload	253 kg
Maximum supplementary load, rotat-	300 kg / 130 kg / 150 kg
ing column / link arm / arm	
Pose repeatability (ISO 9283)	± 0.05 mm
Number of axes	6
Mounting position	Floor
Footprint	754 mm x 754 mm
Weight	approx. 1105 kg
Mounting position Footprint	Floor 754 mm x 754 mm

## Axis data

Motion range	
A1	±185 °
A2	-140 ° / -5 °
A3	-120 ° / 168 °
A4	±350 °
A5	±122.5 °
A6	±350 °
Speed with rated payload	
A1	105 °/s
A2	107 °/s
A3	114 °/s
A4	179 °/s
A5	172 °/s
A6	219 °/s

#### **Operating conditions**

Ambient temperature during opera-	0 °C to 55 °C (273 K to 328 K)
tion	

#### **Protection rating**

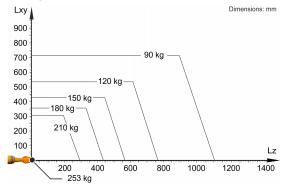
Protection rating (IEC 60529)	IP65
Protection rating, robot wrist (IEC 60529)	IP65 / IP67
Controller	
Controller	KR C5;

Controller	NR 00,
	KR C4

# Certificates

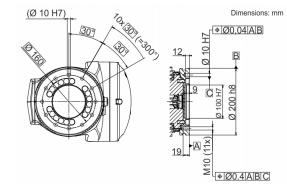
ESD requirements IEC61340-5-1; ANSI/ESD S20.20

Payload diagram



The KR 180 R2900-2 is designed for a rated payload of 180 kg in order to optimize the dynamic performance of the robot. The maximum payload of 253 kg applies only if the position of the center of mass is 0 mm and a supplementary load optimized for the load case is mounted. The specific load case must be verified using KUKA.Load or KUKA Compose. For further consultation, please contact KUKA Support.

#### Mounting flange



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